

A wide-angle photograph of a vast Arctic sea ice landscape. The foreground is dominated by large, white, jagged ice floes. The middle ground shows a dense field of smaller ice floes and leads, extending towards a distant, flat horizon. The sky is filled with heavy, grey clouds, with a bright patch of light breaking through on the right side, suggesting a low sun or moon. The overall color palette is muted, with various shades of white, grey, and blue.

Observing the changing Arctic Ocean with acoustics

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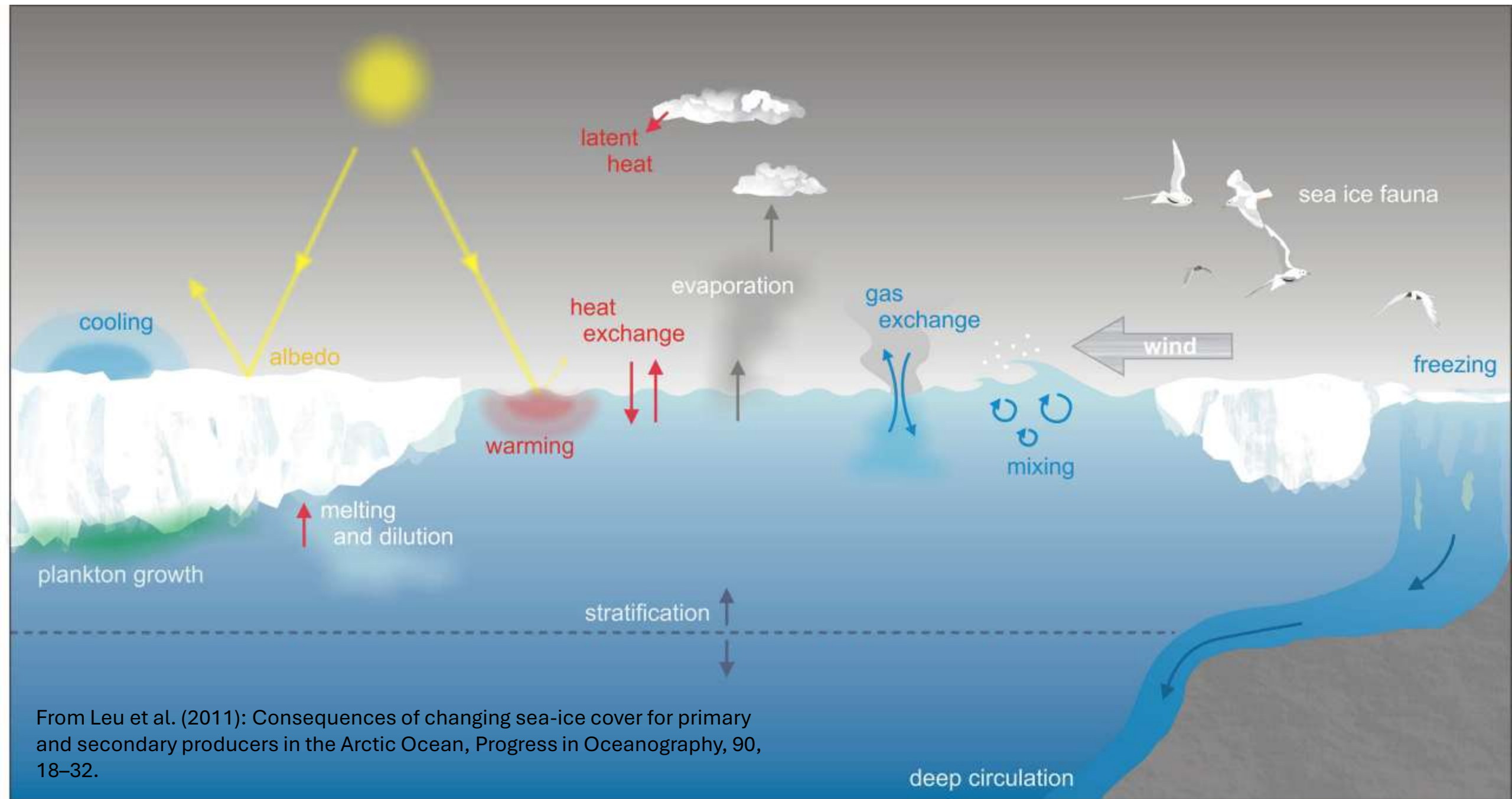
Peter Worcester

Scripps Institution of Oceanography, University of California San Diego

La Jolla, California, USA

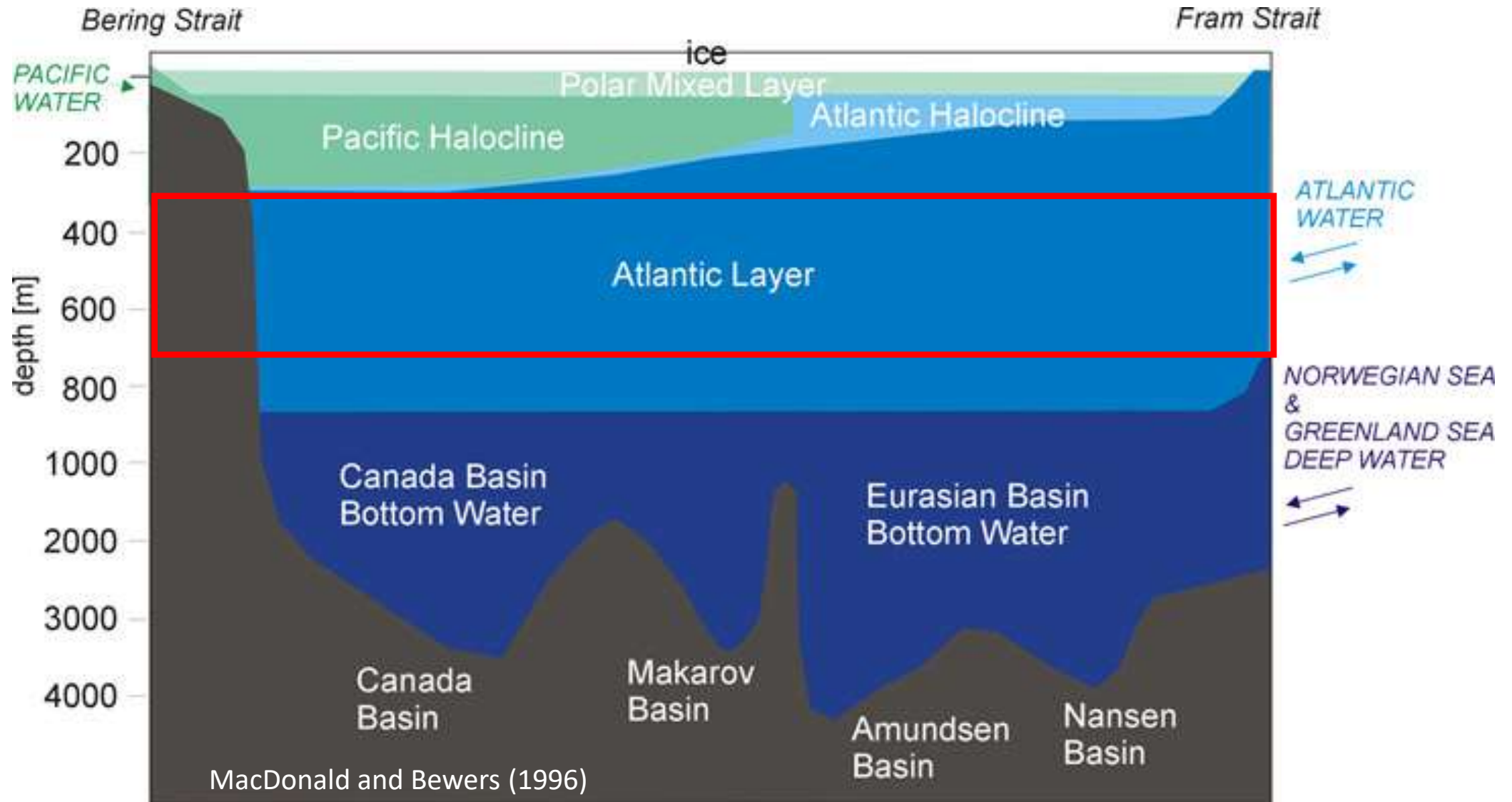
Ice age: 1984 – 2019





From Leu et al. (2011): Consequences of changing sea-ice cover for primary and secondary producers in the Arctic Ocean, *Progress in Oceanography*, 90, 18–32.

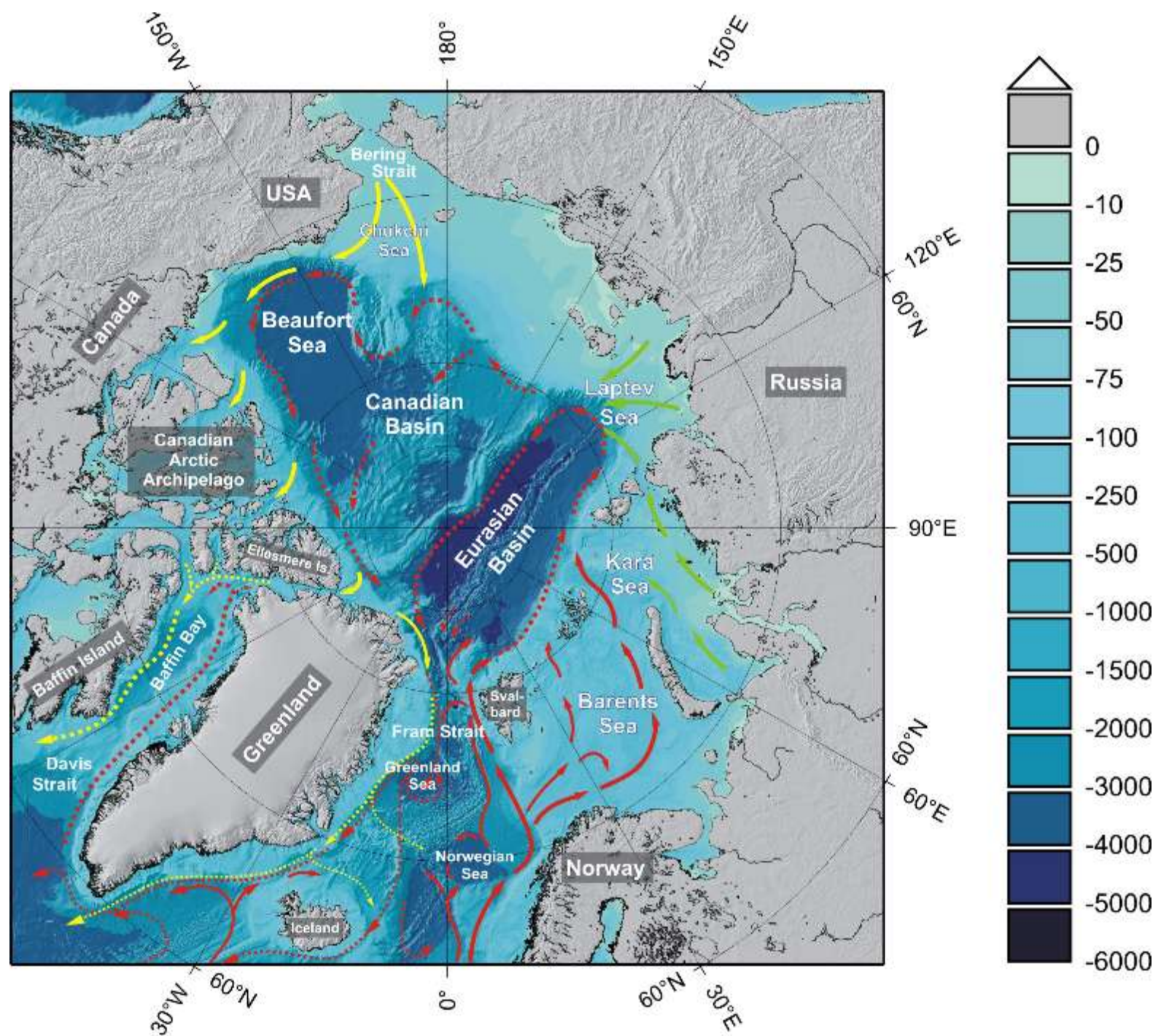
What is happening with the ocean under the sea ice?



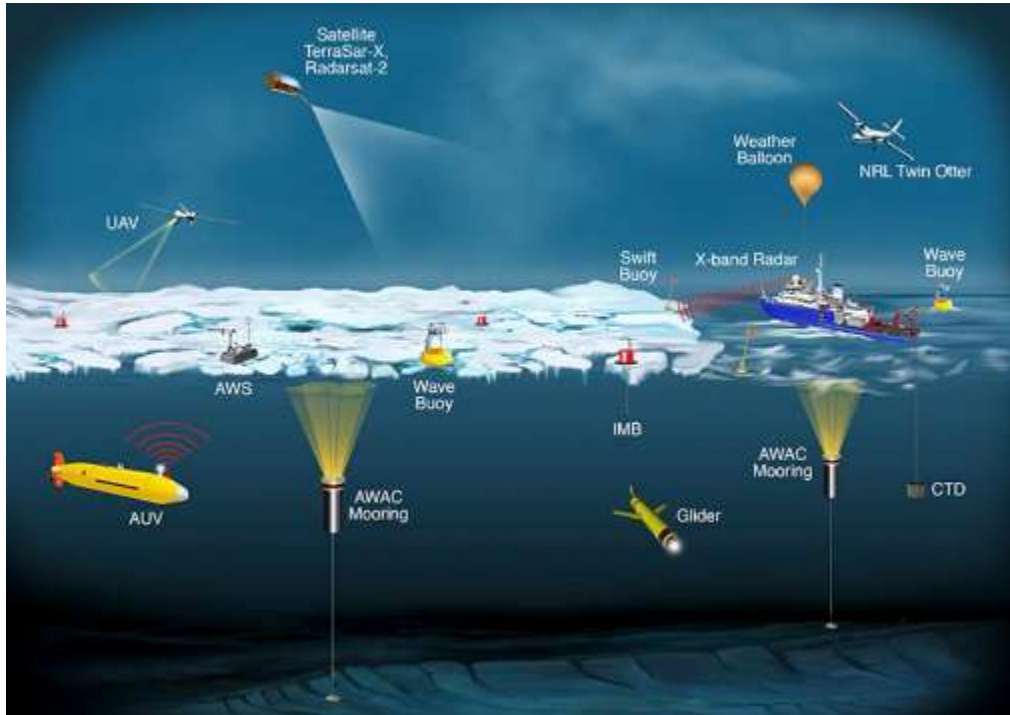
Inflow and circulation of Atlantic water in red and Pacific water in yellow.

Green arrows – fresh-water input from Siberian rivers

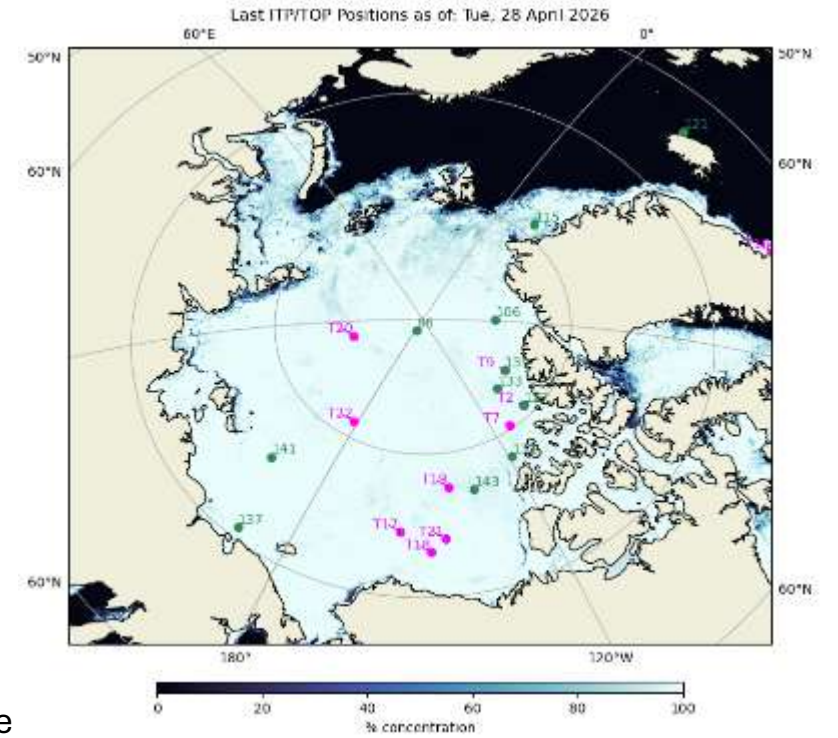
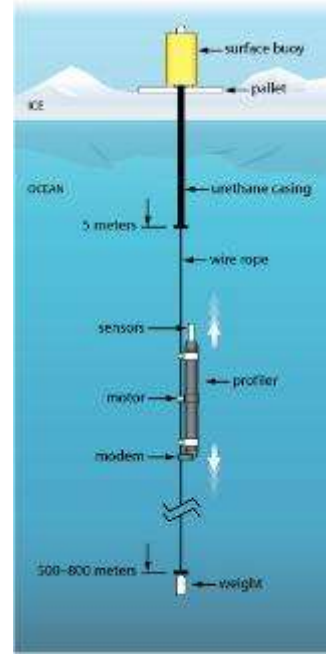
Water resides and circulates for 25 years!



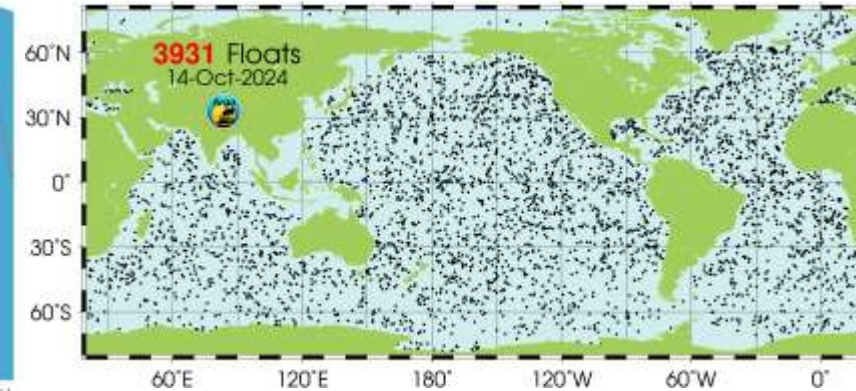
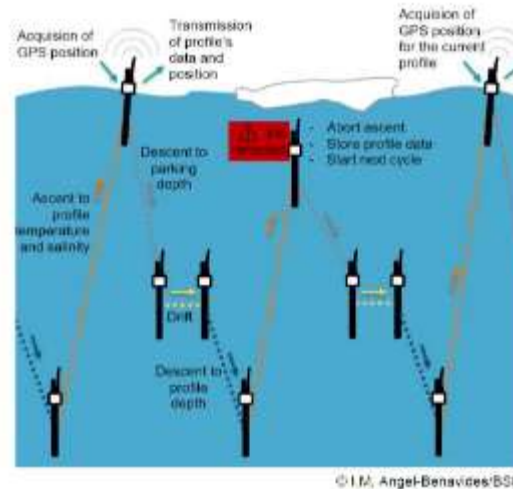
Observing the interior ocean under the Arctic Sea Ice



Thompson et al., 2017

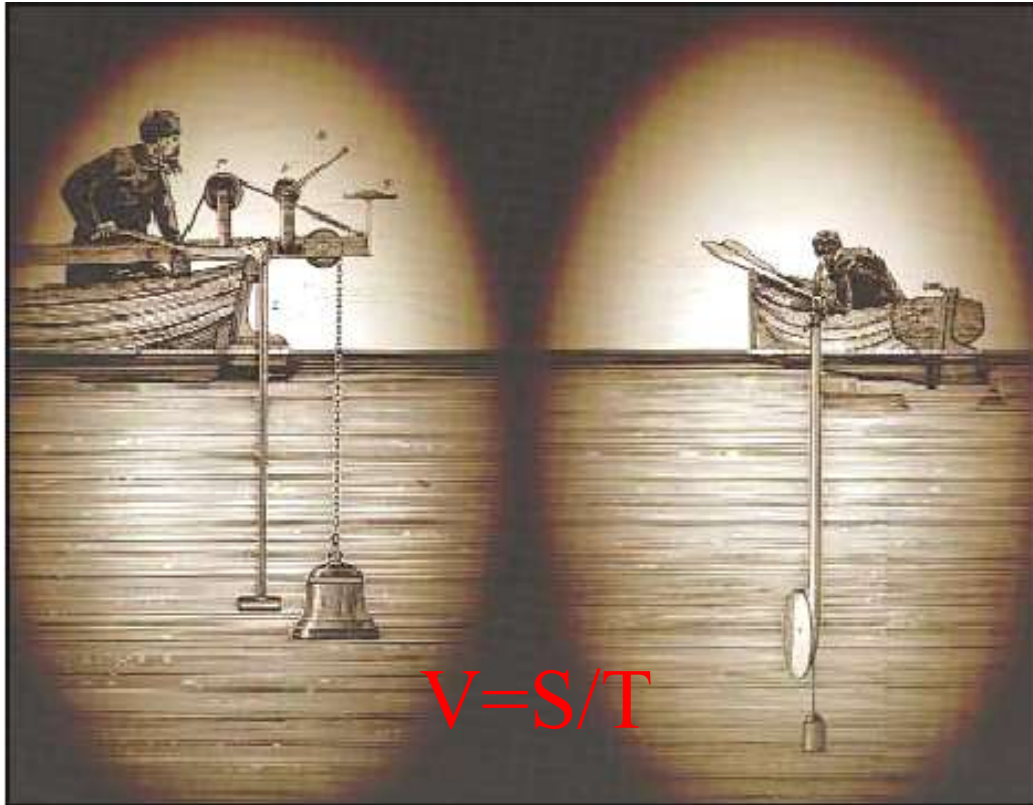


To observe the <https://www2.who.edu/site/itp/data/>



<https://sio-argo.ucsd.edu/statusbig.gif>

Principle of acoustic measurements



- 1826, Colladon and Sturm
- Lake Geneva
- Measure distance (navigation) and time

Acoustic thermometry

Travel time between source receiver – gives sound speed
→ temperature ($V=S/t$)

Acoustic positioning/localization

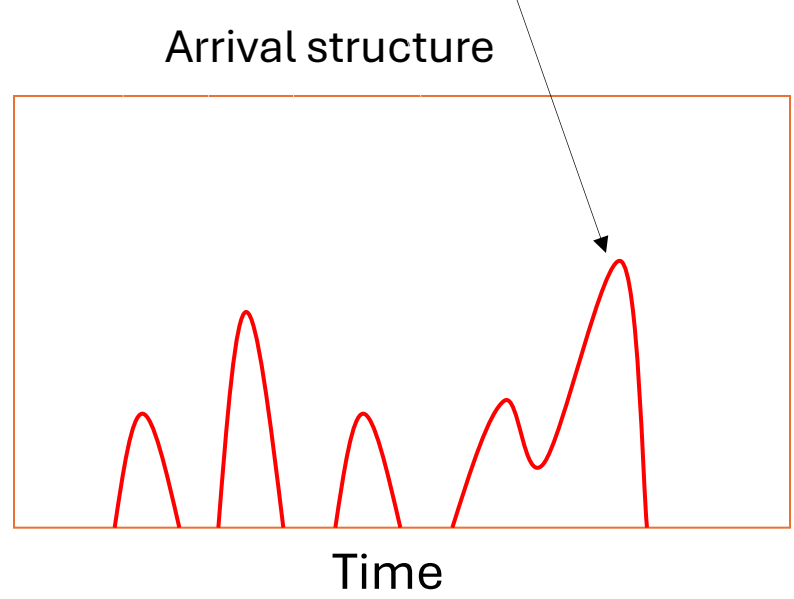
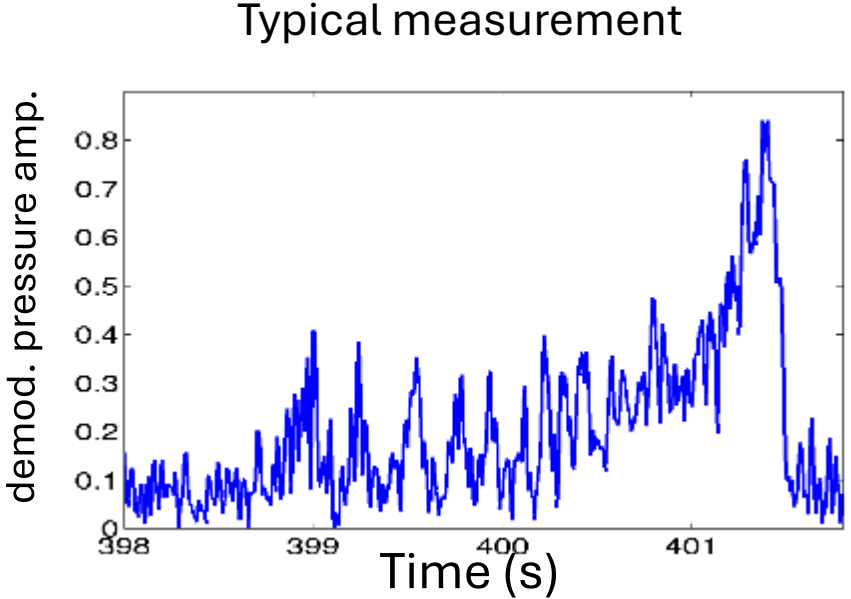
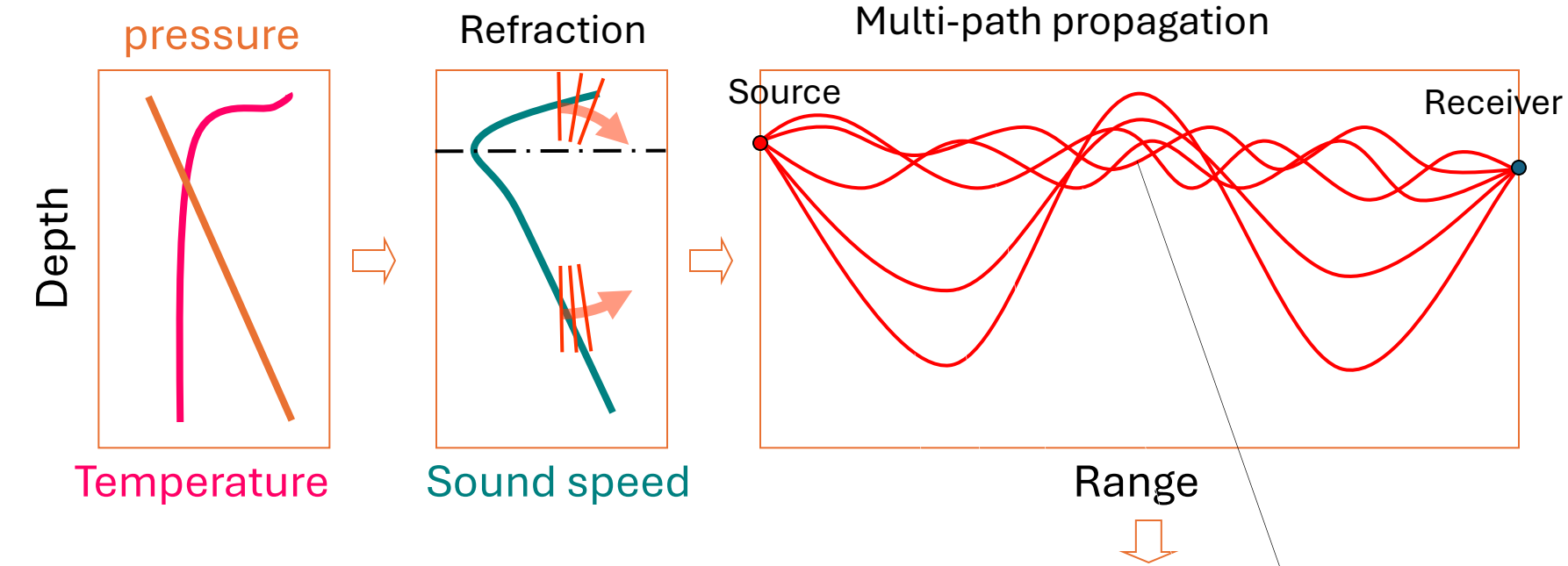
Measure travel time –
known sound speed → gives
 $S=v*t$

Passive listening

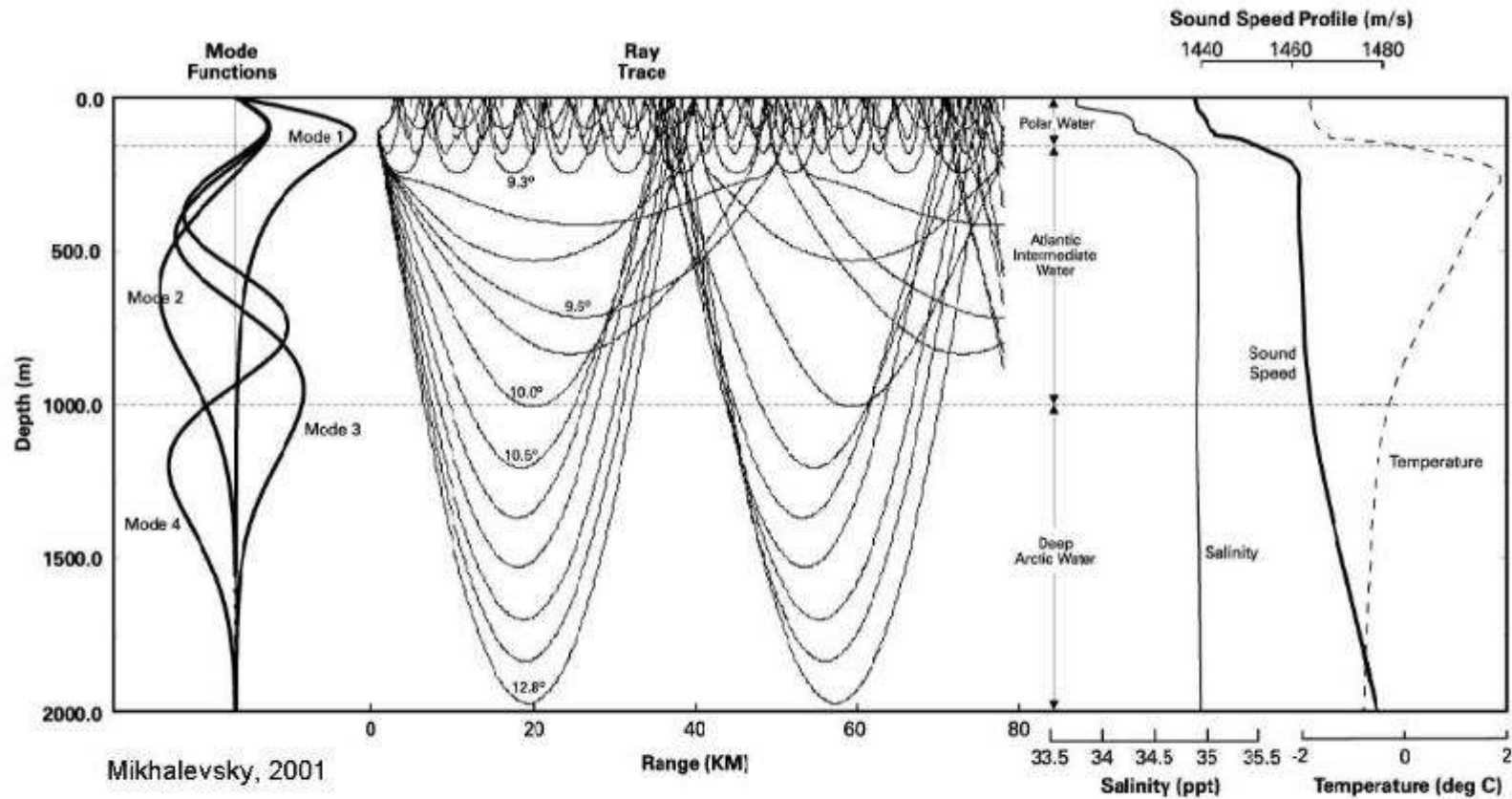
Detect, localize, track sounds
from different human and
natural sources.

Communication

Acoustic propagation in the ocean is a result of how the ocean is structured



ACOUSTIC THERMOMETRY in the ARCTIC OCEAN



MAJOR ARCTIC OCEAN WATER MASSES ARE WELL SAMPLED BY ACOUSTIC MODES/RAYS (Modes shown for 20 Hz)

Mikhalevsky, 2001

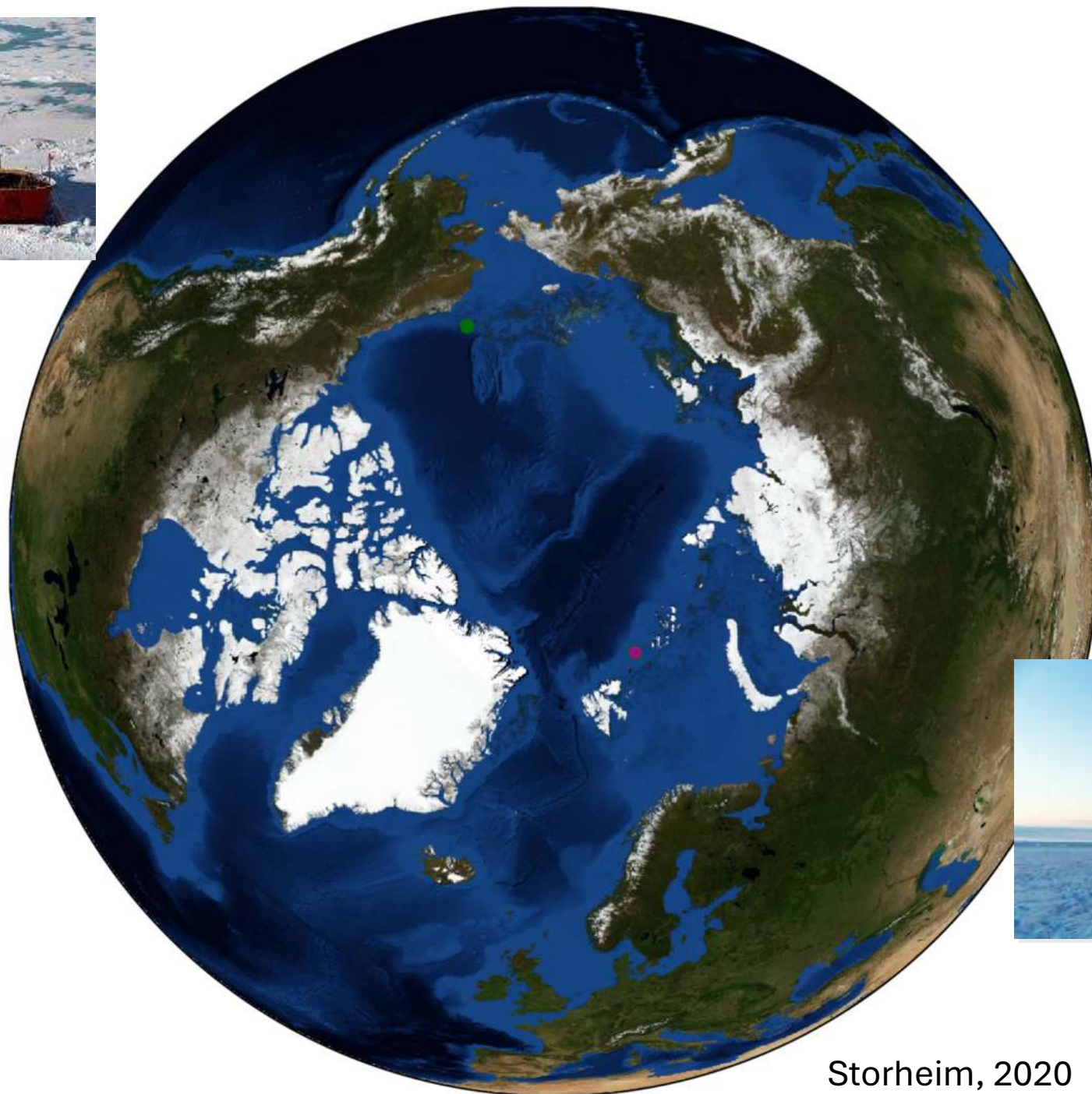


USCGC Healy

Deployment
3.9-14.10 2019

Planned recovery
18.08.2020 –
22.10.2020

Project Lead:
Matthew Dzieciuch
SIO



KV Svalbard
Departure/Return LYR
Deploy
14.08 2019- 9.9 2019

Recover
17.07 2020- 9.8 2020

Project Lead:
Hanne Sagen, NERSC



Storheim, 2020



CAATEX

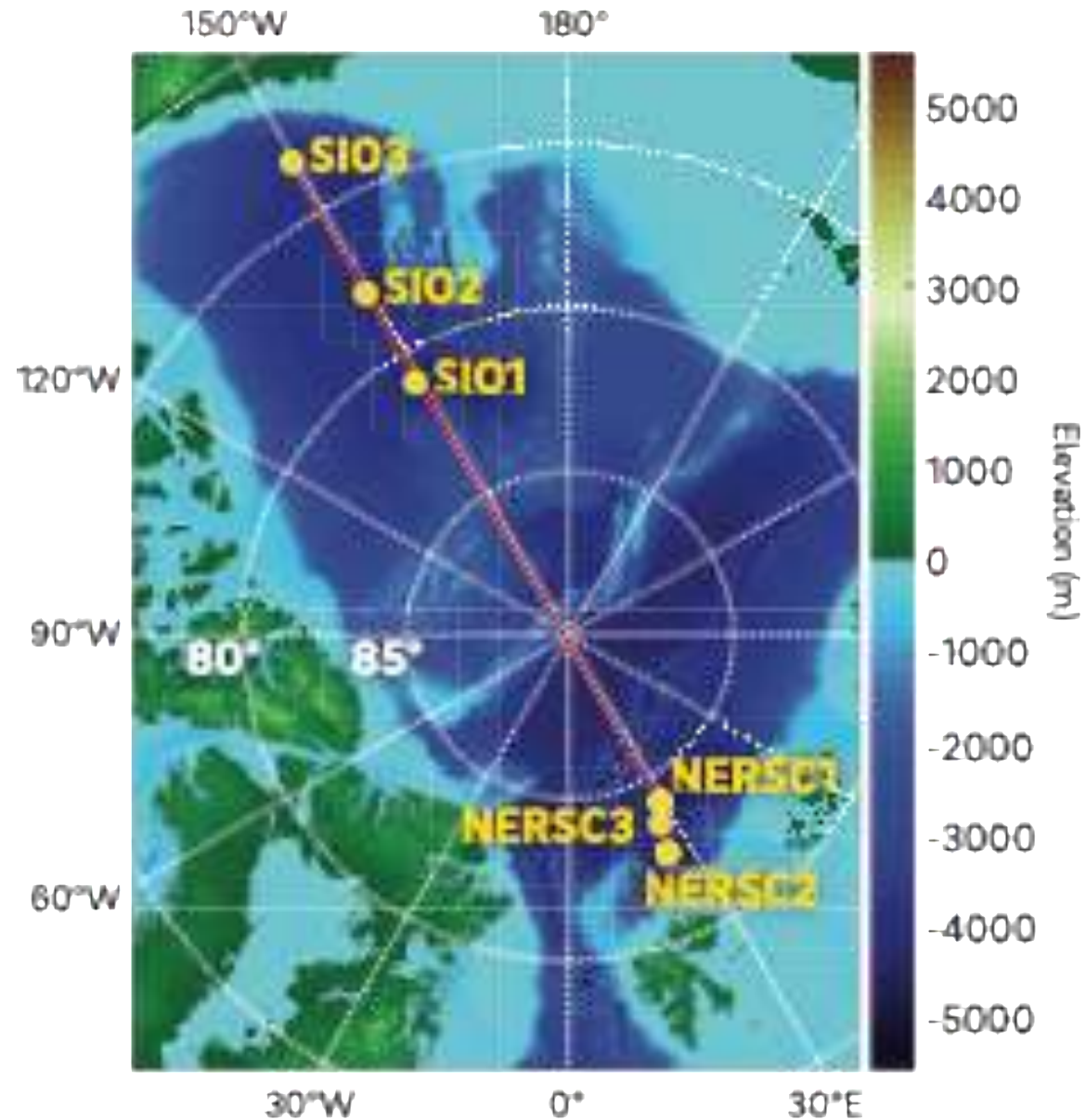
(Coordinated Arctic
Acoustic Thermometry
Experiment)

2019–2020

SIO1, NERSC1:
Source/receiver moorings

SIO2, SIO3, NERSC2,
NERSC3 : Receiver
moorings

Range (NERSC1–SIO3) =
2565.699 km



Dzieciuch et al.
(2026)

CAATEX Mooring SIO1

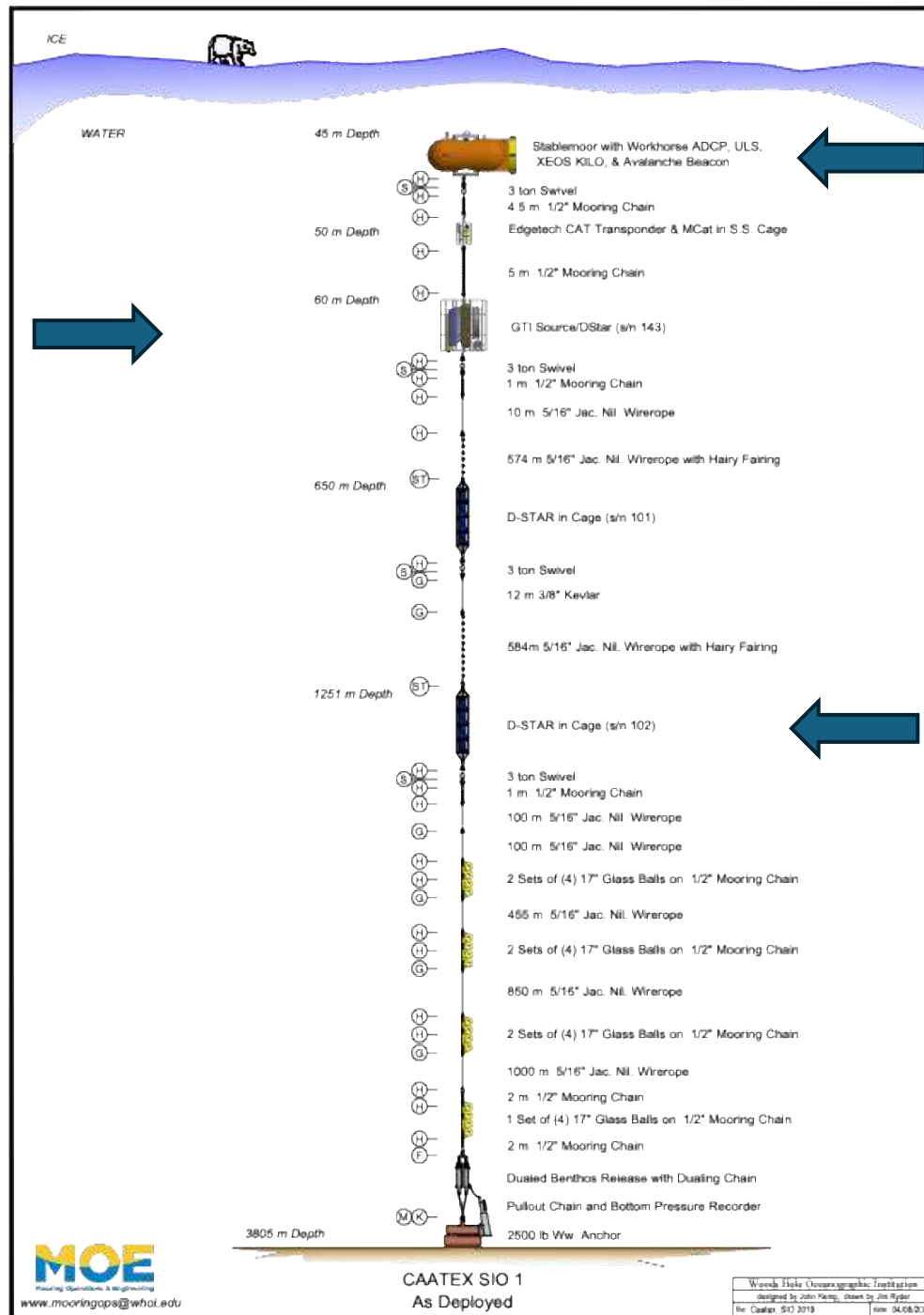


Photo: KV Svalbard Norwegian Coast Guard



Photo: Lloyd Green, SIO



Photo: KV Svalbard Norwegian Coast Guard

CAATEX Source

GTI C-BASS electrodynamic
sound projector

Depth = 60 m

Center frequency = 35 Hz

Bandwidth = 4 Hz

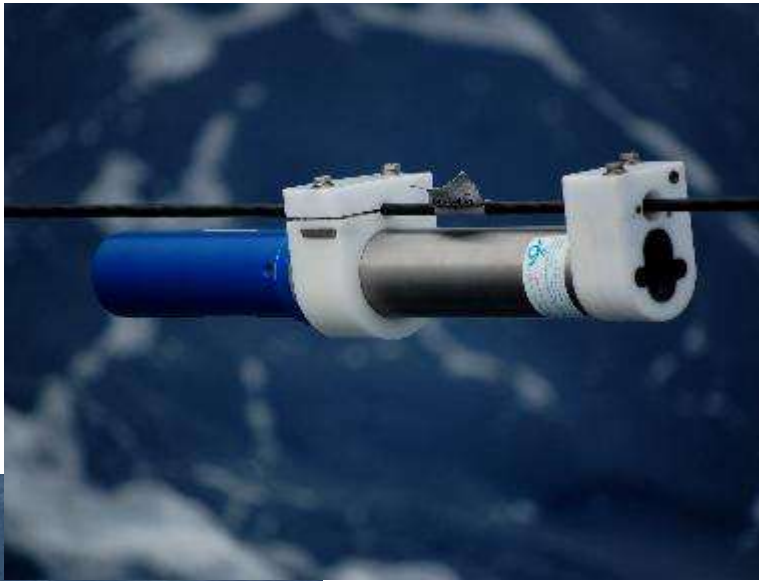
SL = 195 dB re 1 μ Pa @ 1 m

Signal: Phase-coded m-sequence

Duration: 874.286 s



Distributed Vertical Line Array Receiver (DVLA)



Approach

- Distributed, self-recording hydrophone modules
- Timing and scheduling provided by D-STAR controllers

Enabling technologies

- Flash memory modules that store gigabytes of data
- Inductively-coupled modems that use standard mooring wire

SIO moorings: 40 HM @ 30 m spacing
NERSC moorings: 25 HM @ 40 m spacing

Photos: Lloyd Green, SIO

Mooring deployment

Mooring recovery

NORCE



KYSTVERKET

NERSC

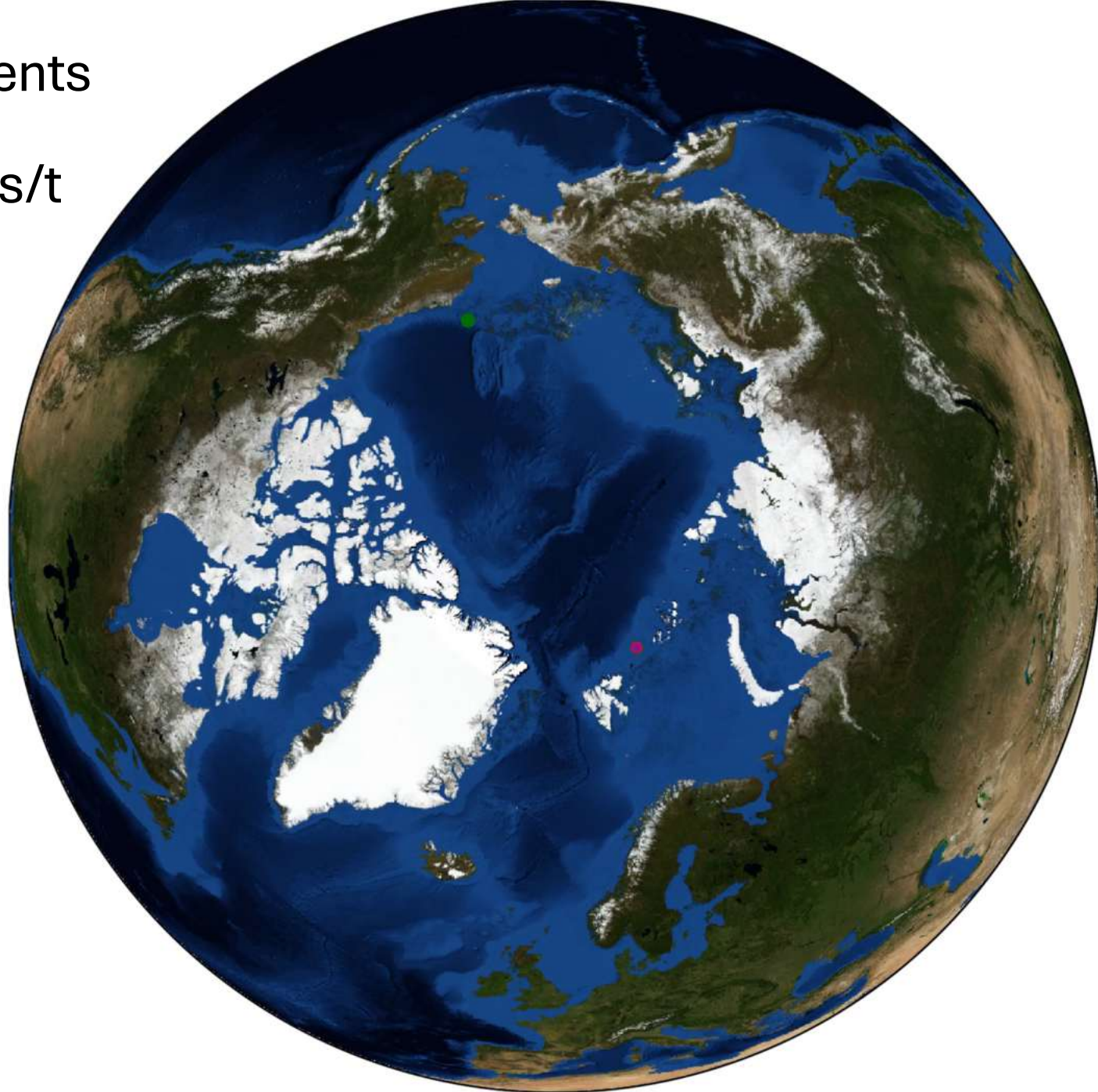
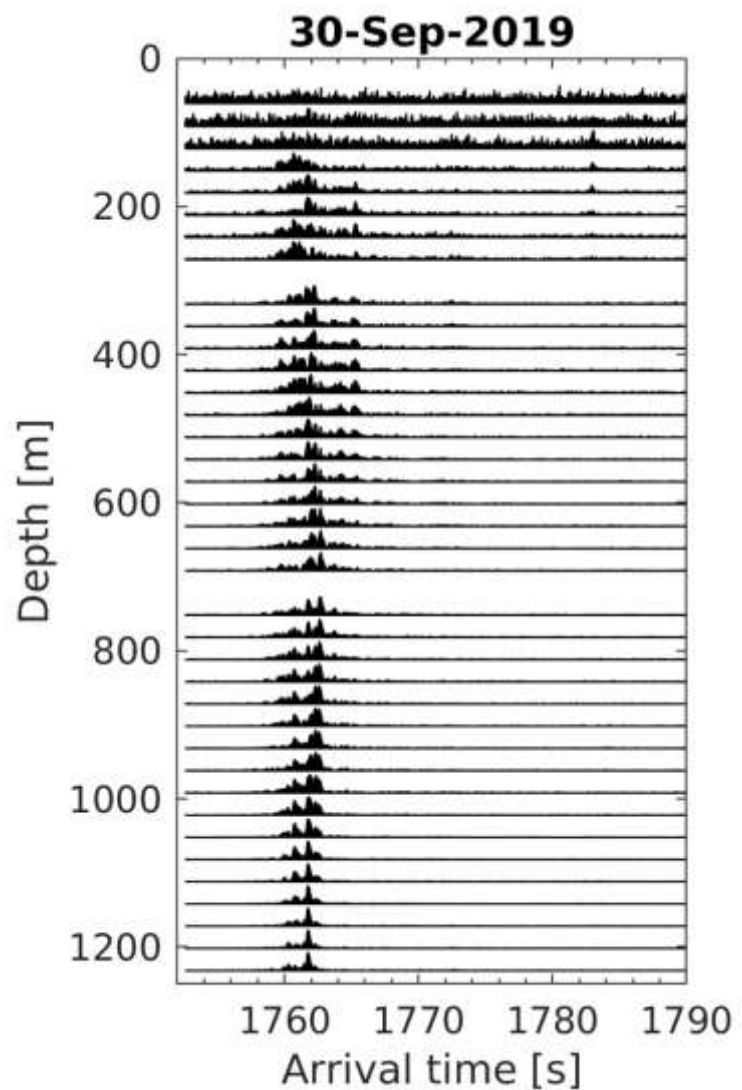
CAATEX



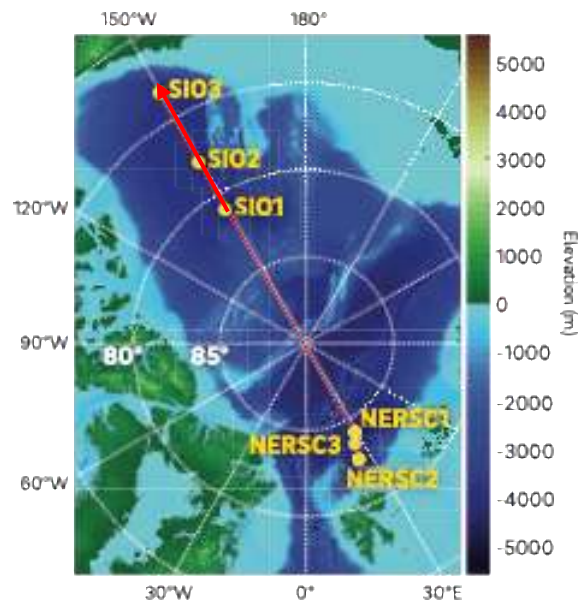
Trans Arctic Acoustic measurements

Acoustic travel times at 2560 km

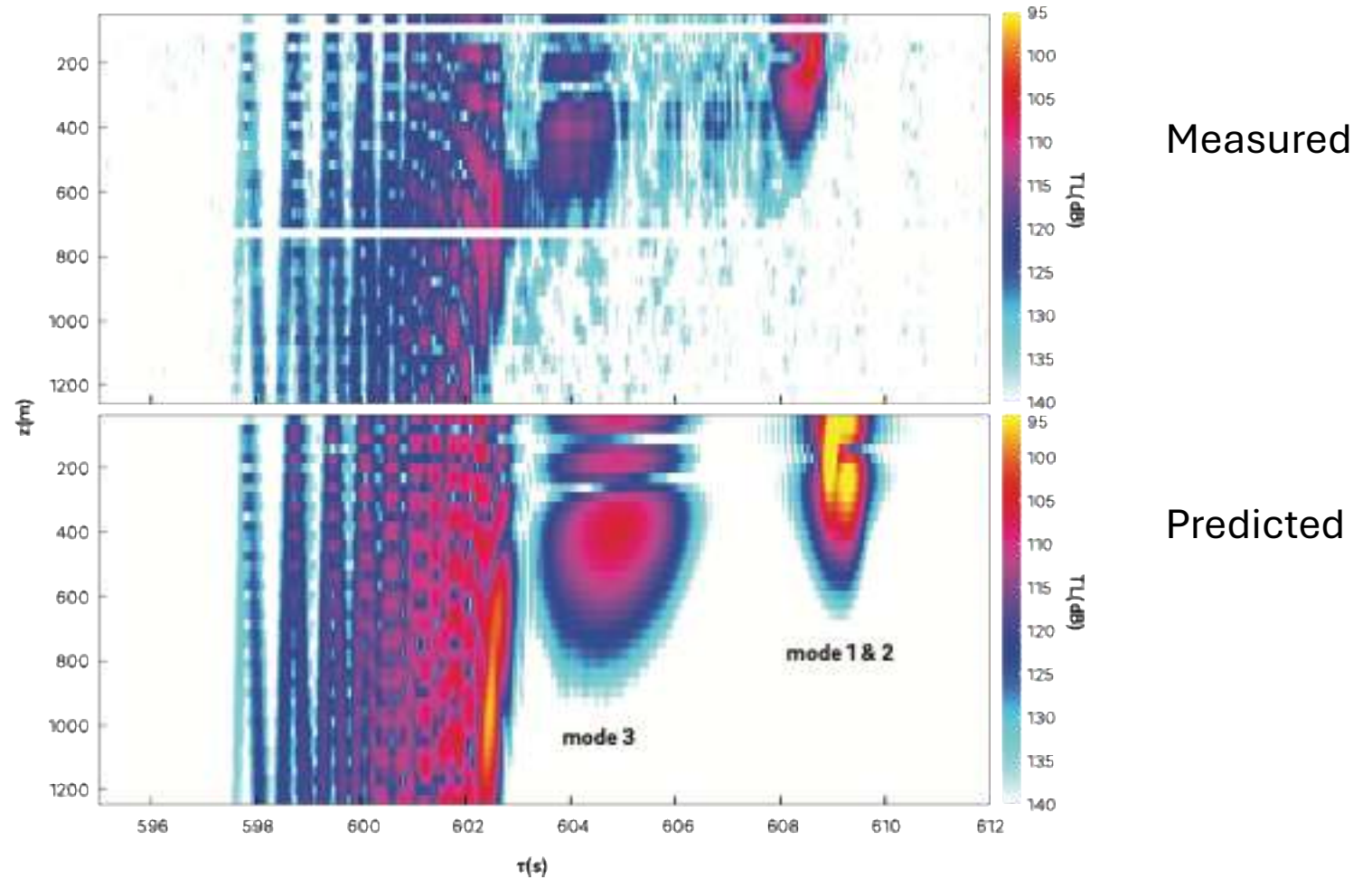
$$C = s/t$$



CAATEX Reception: SIO1–SIO3



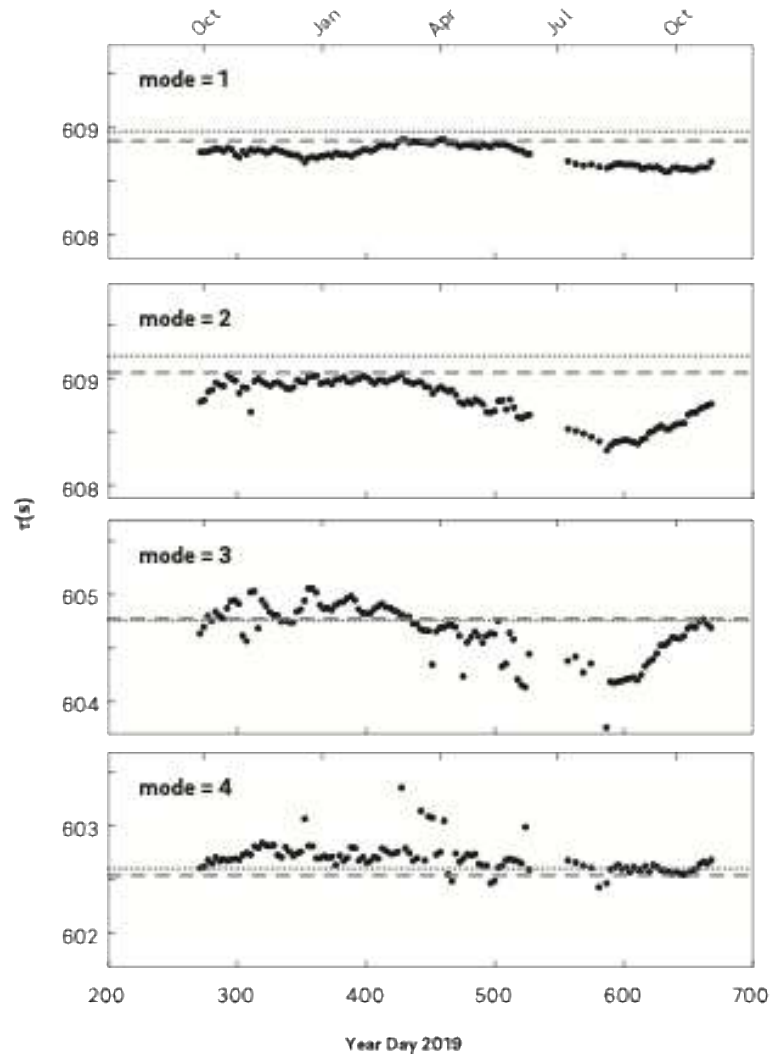
20 August 2020



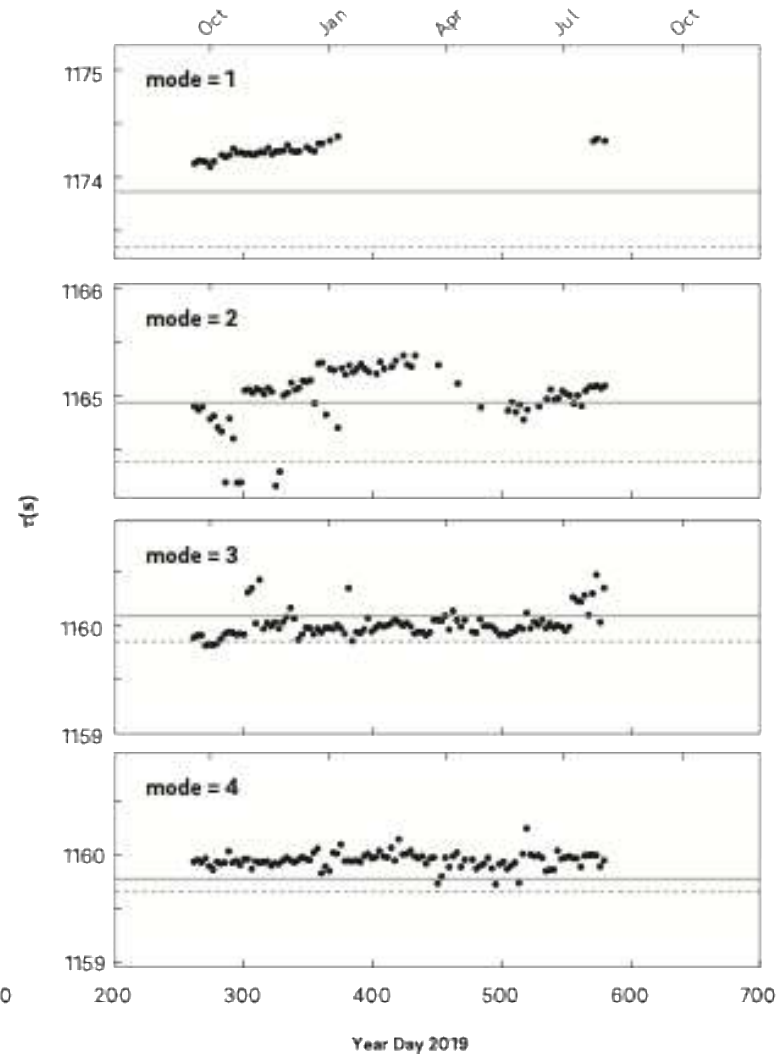
Dzieciuch et al. (2026)

Modal travel times

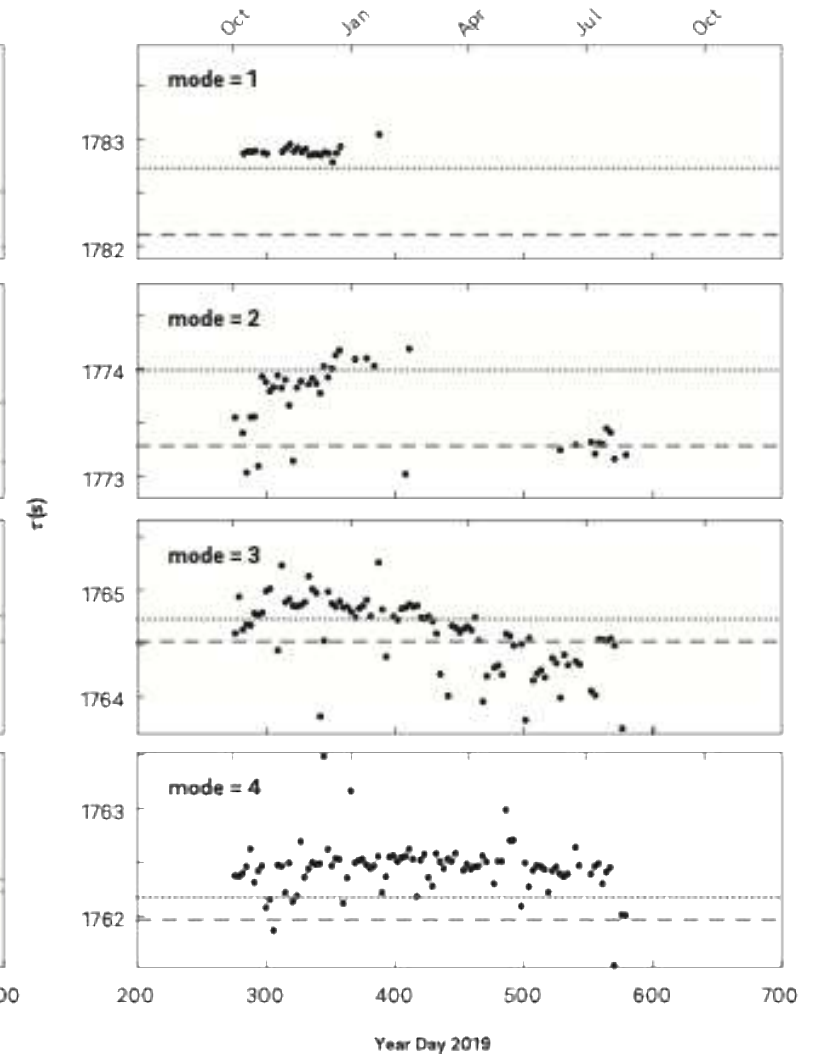
SIO1–SIO3 (877 km)



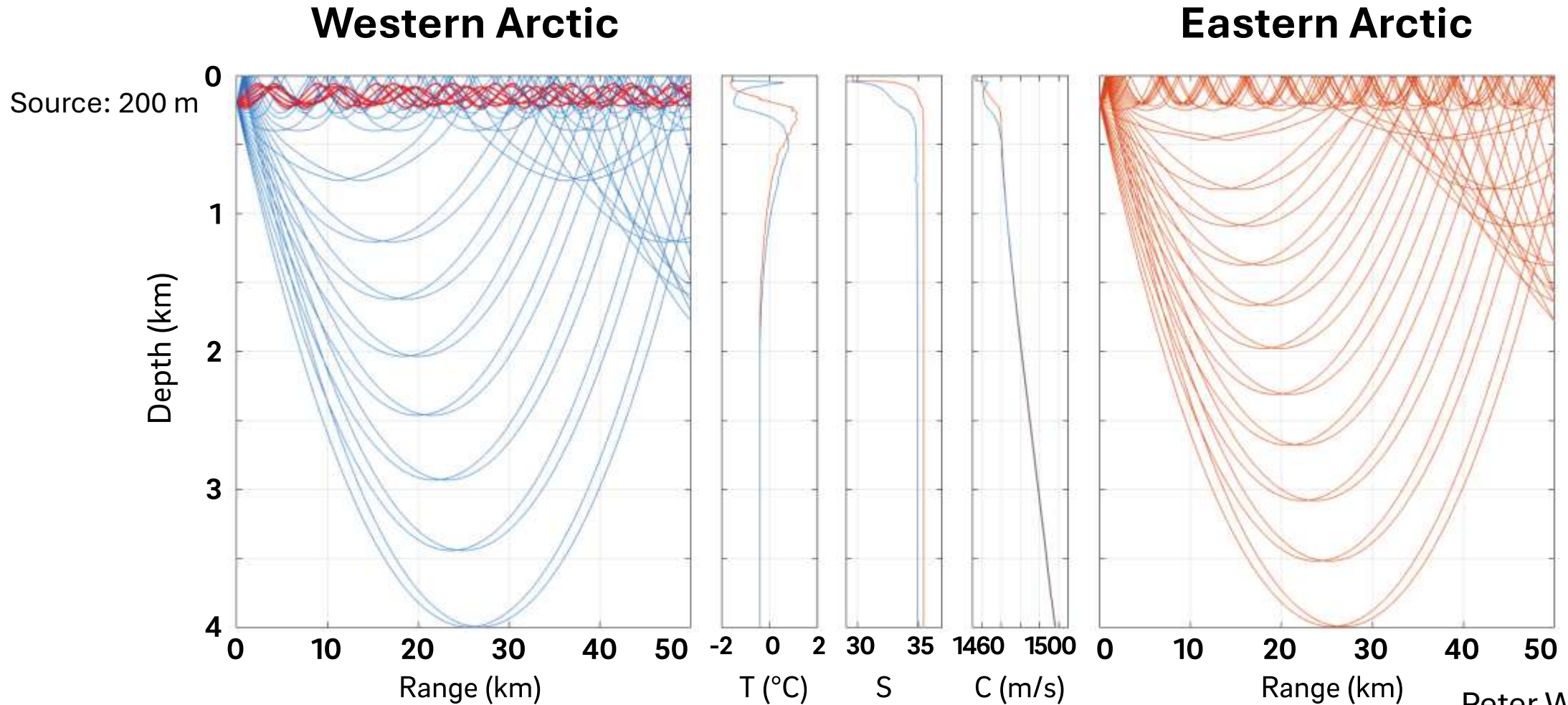
NERSC1–SIO1 (1689 km)



NERSC1–SIO3 (2566 km)



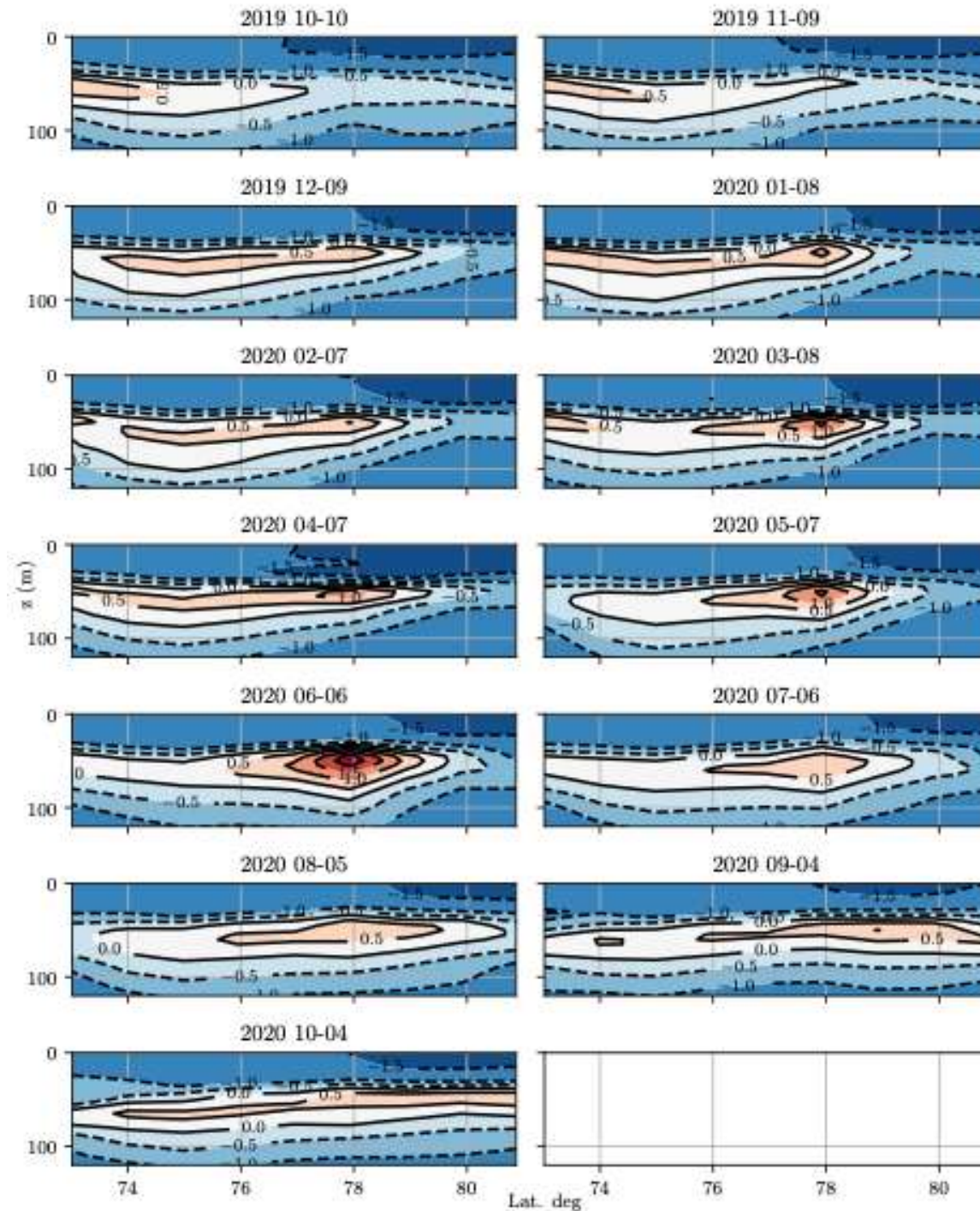
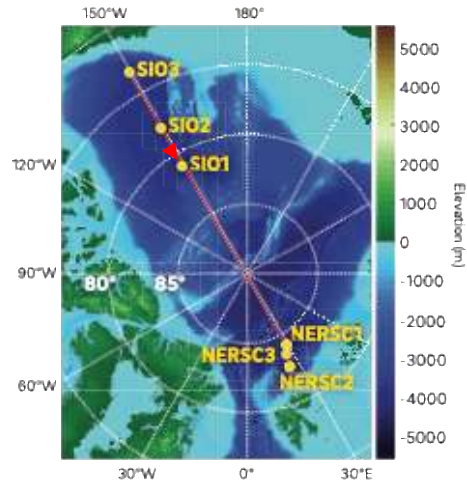
Acoustic propagation: Western vs. eastern Arctic Ocean



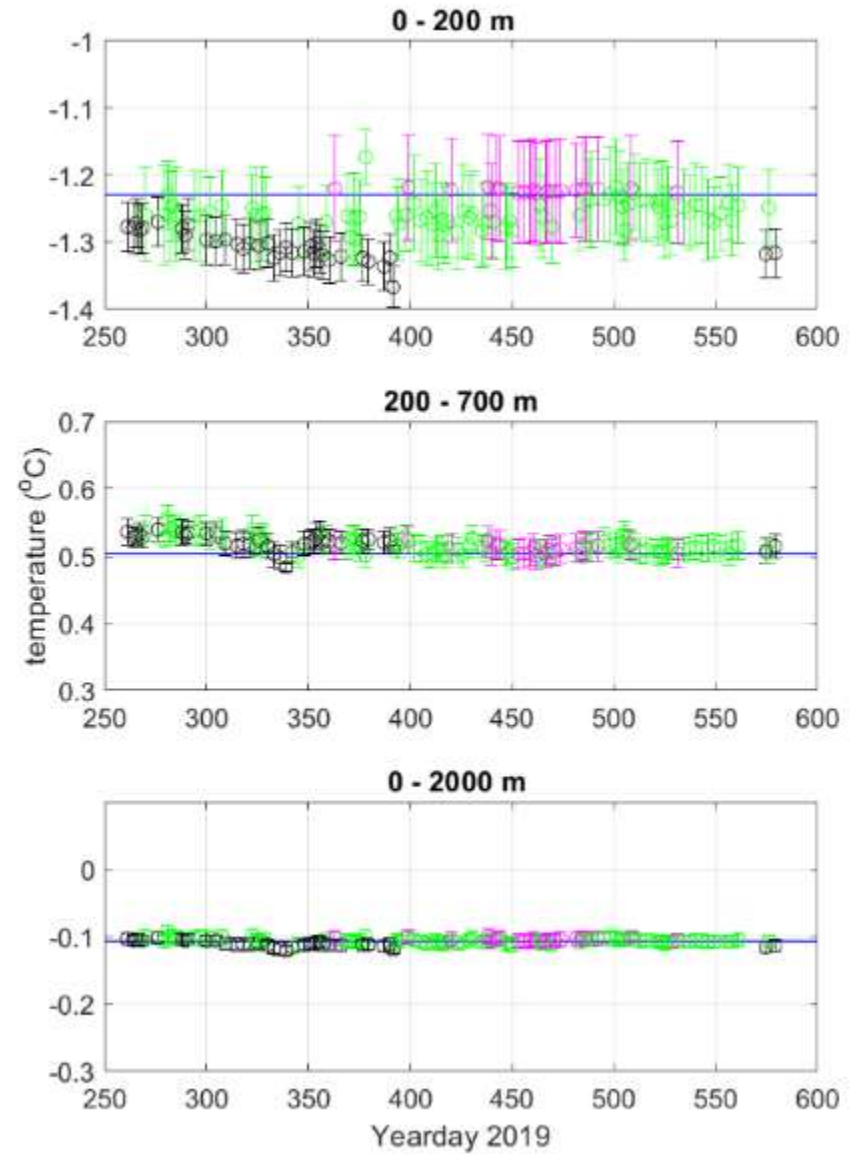
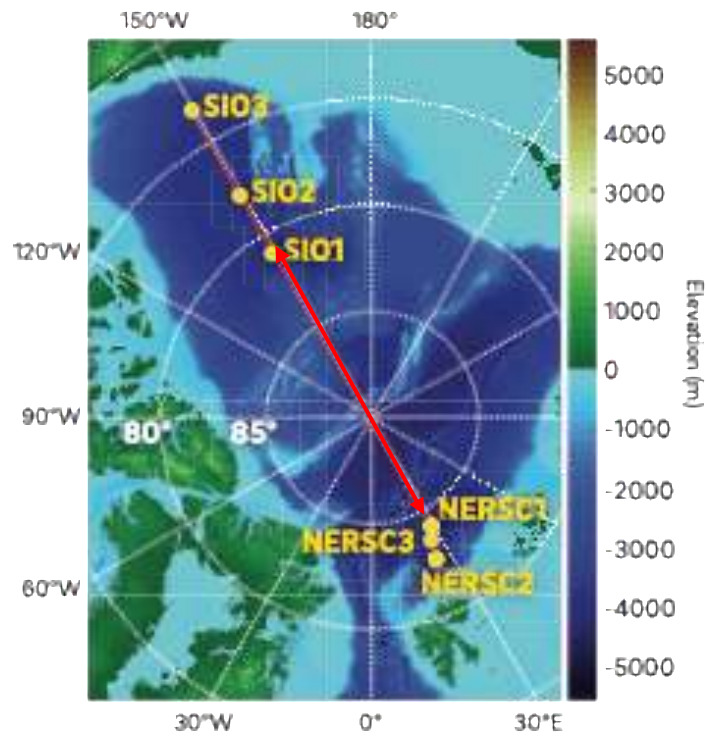
Temperature: SIO1–SIO3

Depth: 0–120 m
Monthly averages
0.5°C contours

Pacific Summer Water:
~ 70 m depth



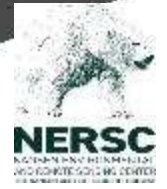
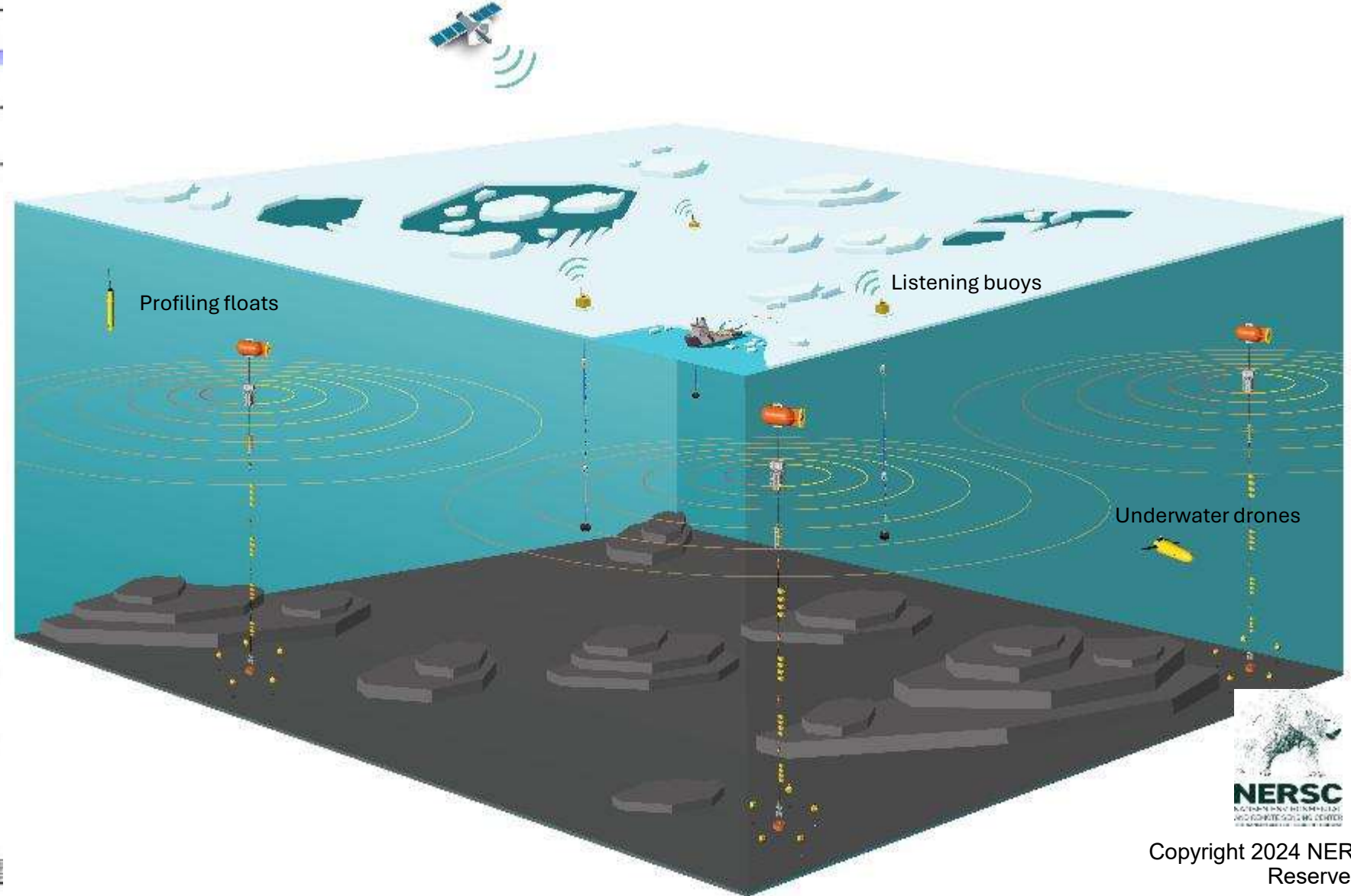
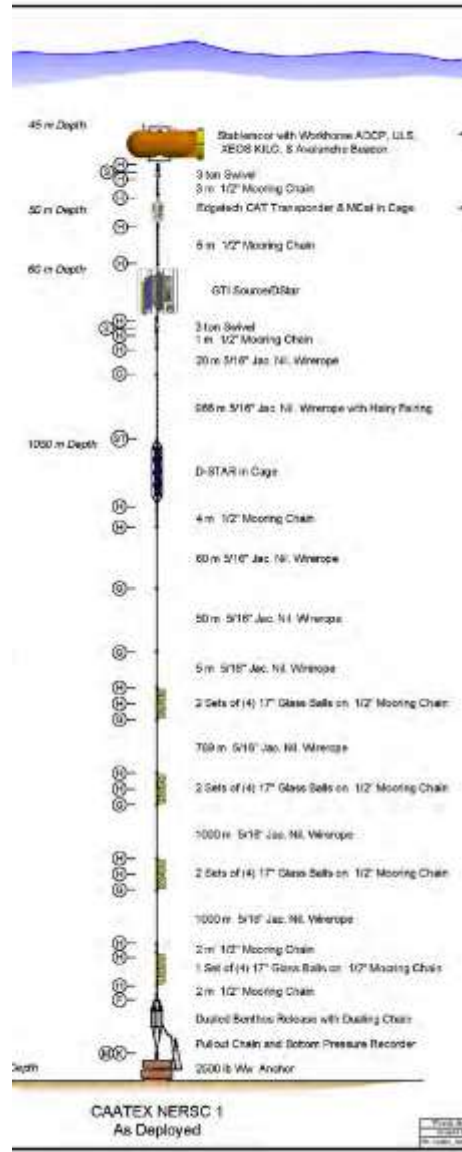
Mean Ocean Temperature: NERSC1–SIO1





Moored system for basin wide ocean observations, acoustic thermometry, passive acoustics and underwater GPS in Nansen and Amundsen Basins

Source moored



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HiA00S

Acoustic thermometry

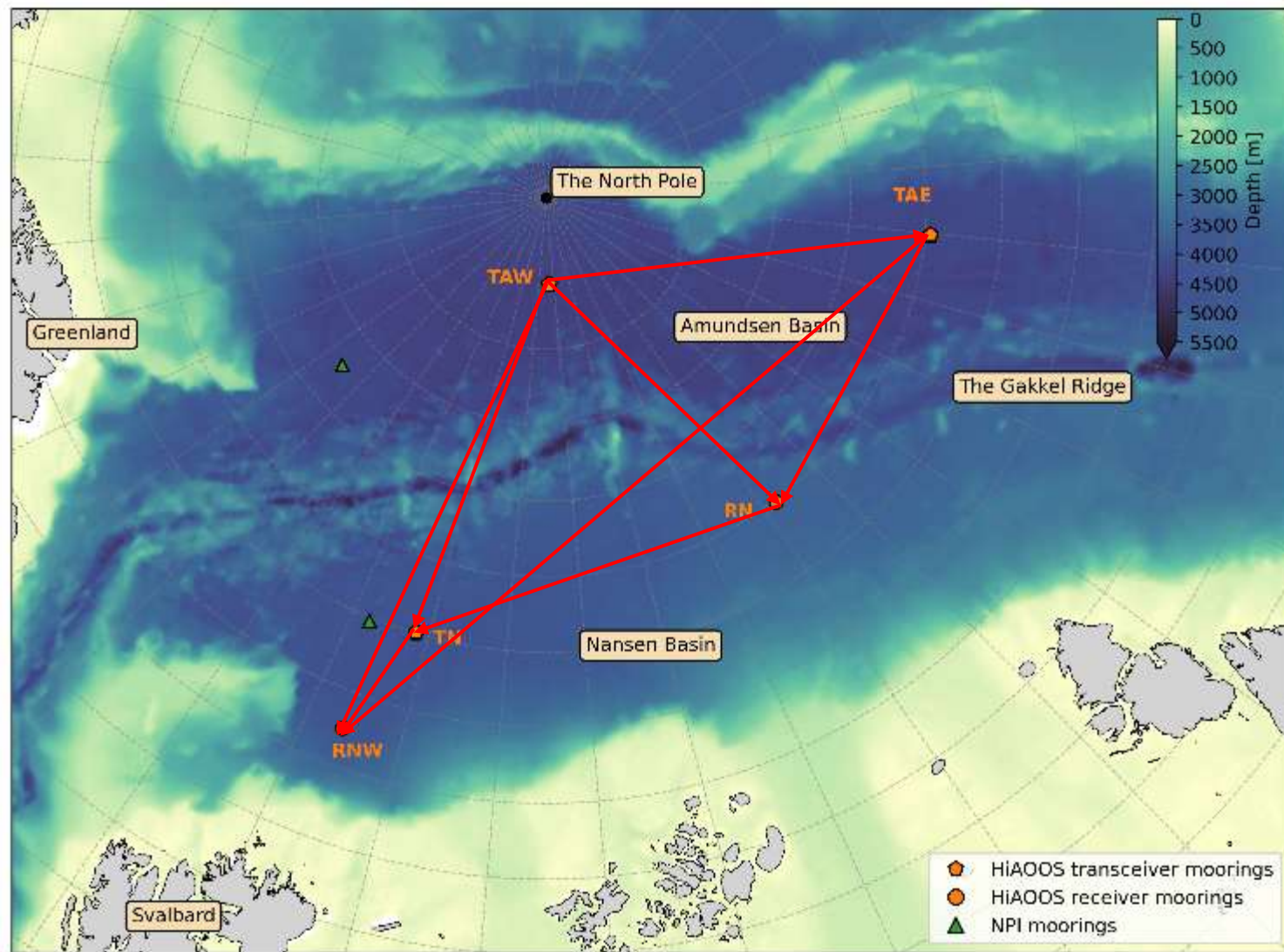
HiAATS

2024 (August - September):

Deployed mooring network in the Nansen and Amundsen Basin. Sources transmit 7 minutes *m*-sequences at 35 Hz every 2 days for 2 years.

2026: (August- September)

Full recovery of all the mooring systems to download data and start analysis.

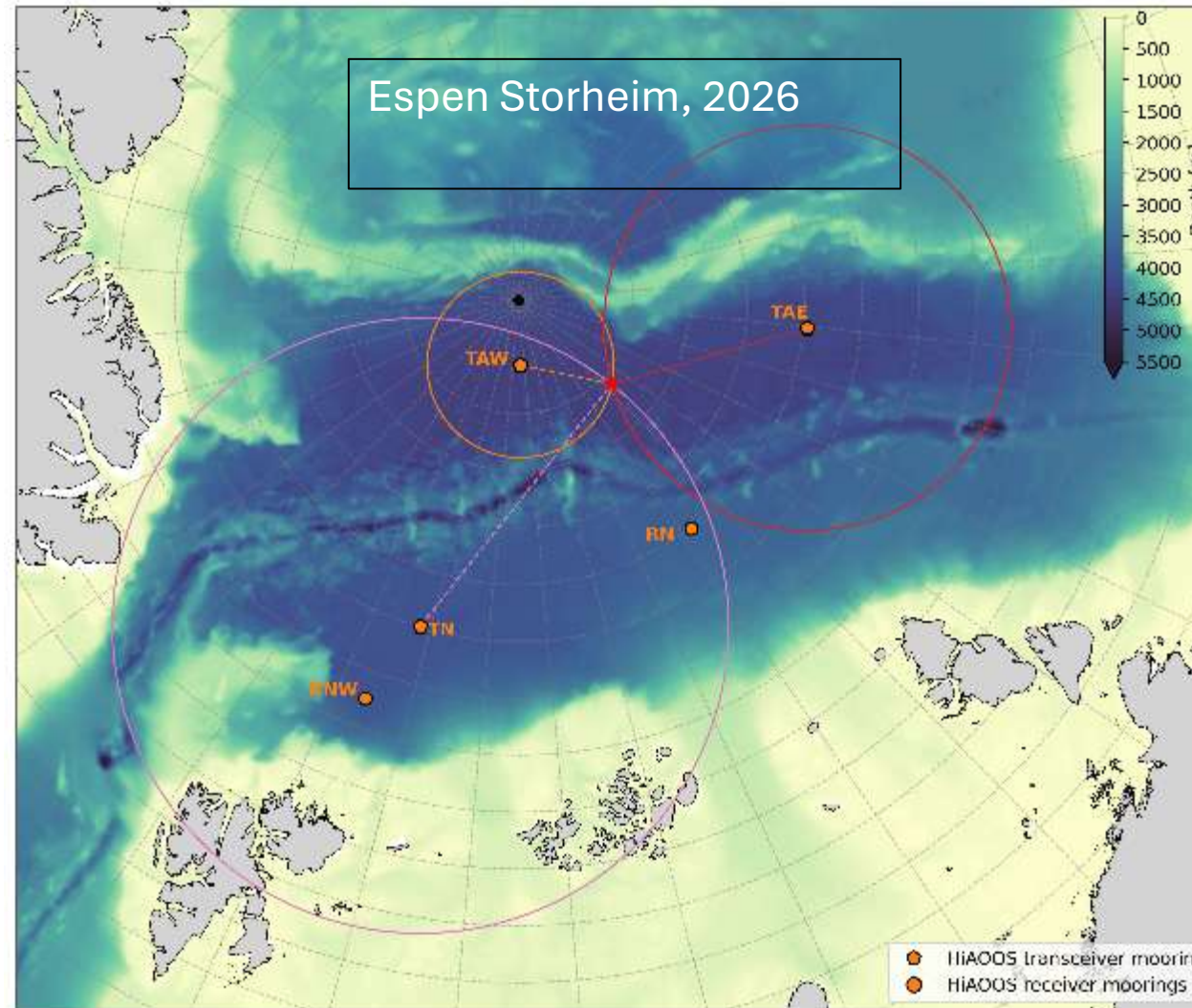


HiA00S: Underwater GPS

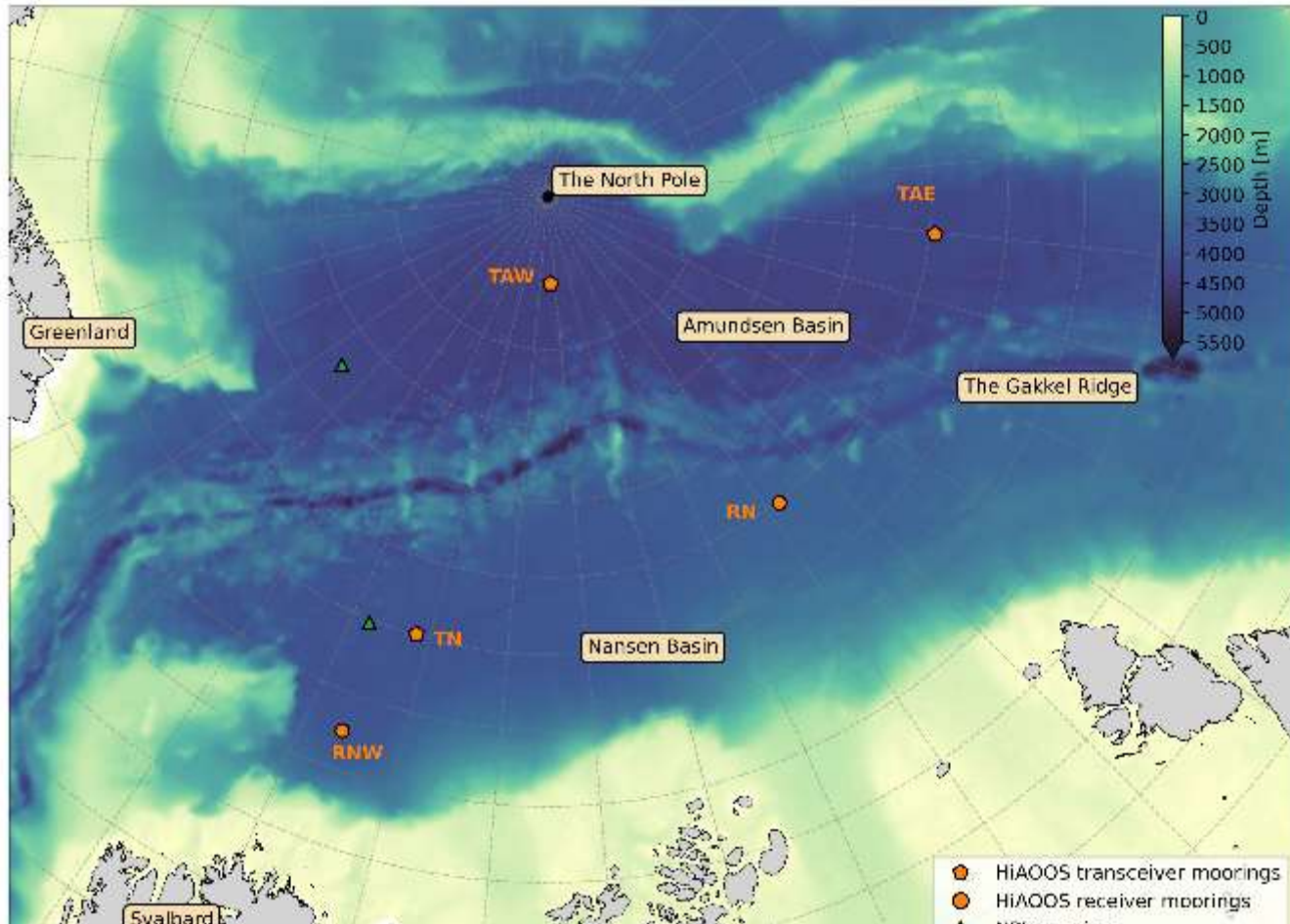
- **Objective:**
Geo-locate floats under the ice using 35 Hz acoustic signals from the HiA00S observing system

Procedure for localization

- Detect accurate arrivals of the signals from minimum 3 sources
- Assume the sound speed profiles are known.
- Calculate distances from the sources and find the intersection of the circles.



Our goal is to sustain long-term ice-ocean observations in the Eurasian Basin.



- An integrated and sustained multipurpose underwater system will support multidisciplinary research and climate monitoring in the Arctic Ocean the coming years
- This will lead up to IPY 5 - 2032-2033.
- UW-GPS will make it possible to expand the Argo program into the Arctic Ocean.
- Development of robust and autonomous systems will reduce the footprint of research programs in the Arctic.



HiA00S

CAATEX

Coordinated Arctic Acoustic Thermometry Experiment



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HiAATS



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